

EECI-IGSC Course Networked Model Predictive Control for Multi-Vehicle Decision-Making

Dr.-Ing. Bassam Alrifaee | Patrick Scheffe, M. Sc. 2021

Part 1 Introduction

#### **Your instructors**



Bassam Alrifaee <u>alrifaee@embedded.rwth-aachen.de</u> Lectures



Patrick Scheffe <u>scheffe@embedded.rwth-aachen.de</u> Lab, Organization

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- Founded 1870
- Largest technical university in Germany
- 45.000 students, 6.500 graduates per year
- >20% international students, from 128 countries
- 9500 staff, 540 professors
- 900 million € expenditure

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- >400 million € third party funding (biggest amount in Germany, in total and per professor)
- Highest number of alumni as CEOs in DAX companies





### Nine schools ("Fakultäten"):

- **1** Natural Sciences, Computer Science, and Mathematics
- 2 Architecture
- 3 Civil Engineering
- 4 Mechanical Engineering
- 5 Mining and Materials
- 6 Electrical Engineering
- 7 Philosophy
- 8 Economics

10 Medicine

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1	Natural Sciences, Computer Science, and Mathematics				
	Biology				
	Chemistry				
	<b>Computer Science</b>	<ul> <li>~ 3500 students</li> <li>&gt; 450 graduates</li> <li>~ 30 Professors</li> </ul>			
	Mathematics				
	Physics				
4	Mechanical Engineering	<ul> <li>~ 10.000 students</li> <li>~ 2.000 graduates, 200 PhDs in 2014</li> <li>~ 60 Professors</li> </ul>			



#### **Computer Science**

Computer Science					
	1	Algorithms			
	2	Software Theory			
	3	Software Engineering			
	4	Distributed Systems			
	5	Information Systems			
	6	Speech Recognition			
	7	Logics and Automata			
	8	Computer Graphics			
	9	Data Mining			
	10	Human Computer Interaction			
	11	Embedded Software			
	12	High Performance Computing			
	13	Computer Vision			



#### Informatik 11 - Embedded Software (i11)



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## Informatik 11 - Embedded Software (i11)

- Head: Prof. Stefan Kowalewski (since 2003)
- Ca. 20 researchers, 4 non-academic employees, 5 apprentices
- > 1.600 students per year in our courses
- Ca. 40 graduates per year (15 Bachelor and 25 Master)
- Spin-off companies in the last five years

## Informatik 11 - Embedded Software (i11)

**Biomedical Systems** (5 researchers)

- Head: Dr. André Stollenwerk
- Supervision of medical devices

Data analysis

## Cyber-Physical Mobility (7 researchers)

- Head: Dr. Bassam Alrifaee
- Networked control systems
- Service-oriented architectures

Formal Methods (4 researchers)

- Head: Marcus Völker, M. Sc.
- Verification of CPS
- Application: industry automation



## **Profile of Cyber-Physical Mobility Group**







#### **Members of Cyber-Physical Mobility Group**



- 23 Master's and Bachelor's students
- 6 students in Team GalaXIs (our student team participating at Carolo-Cup)



# **Participants**

Shortly introduce yourself, e.g., with your ...

Name

Topic

Progress

Motivation/Expectation

![](_page_13_Picture_6.jpeg)

**CPM Lab Visit** 

#### **CPM Lab virtual visit**

![](_page_15_Figure_1.jpeg)

https://cpm.embedded.rwth-aachen.de/

![](_page_15_Picture_4.jpeg)

#### **Movie of 150 years of RWTH**

## https://youtu.be/RBuqHPCQPGo?t=428

![](_page_16_Picture_2.jpeg)

![](_page_16_Picture_4.jpeg)

#### **CPM Lab motivation**

#### Lab-Vision: See your ideas develop into reality!

![](_page_17_Figure_2.jpeg)

![](_page_17_Picture_3.jpeg)

![](_page_17_Picture_4.jpeg)

**Simulation** Test your ideas in a simulation environment

**CPM Lab** See your ideas work in a model-scale testing platform Real World Apply your ideas to real world scenarios

https://cpm.embedded.rwth-aachen.de

![](_page_17_Picture_9.jpeg)

![](_page_17_Picture_10.jpeg)

## **CPM Lab main features**

### **Open source, remotely accessible platform**

- Open code, plans, and documentation
- Remote access via web

## **Rapid algorithm prototyping**

- 20 networked model-scale vehicles (µCars)
- Centralized and distributed computations

## Hierarchical service-oriented architecture

- High- for complex computations, mid- and low-level
- Middleware for data exchange and synchronization

![](_page_18_Figure_10.jpeg)

![](_page_18_Picture_11.jpeg)

![](_page_18_Picture_12.jpeg)

#### **CPM Lab architecture**

![](_page_19_Figure_1.jpeg)

![](_page_19_Picture_3.jpeg)

![](_page_20_Picture_0.jpeg)

https://cpm.embedded.rwth-aachen.de/

**Course Logistics** 

#### **Course contents**

- Vehicle models
- Control and optimization
- Network and distribution
- Software architectures and testing concepts

- Course materials will be posted on Sciebo
- Lab will allow you to apply techniques on real model-scale vehicles

![](_page_22_Figure_7.jpeg)

![](_page_22_Picture_9.jpeg)

#### Lab – apply techniques from lectures

![](_page_23_Figure_1.jpeg)

![](_page_23_Picture_3.jpeg)

![](_page_23_Picture_4.jpeg)

## Logistics

- Lecture style
  - Presentation
  - Group discussions

## Participation

- Attendance list
- Prize for lab work
  - Donation of 15€ per working solution for a good cause
  - Invitation of best solution for a week
- Diagnostic test results

![](_page_24_Picture_10.jpeg)

EECI IGSC	2021 On	line		Module M05		
15.03	.2021-19.03	8.2021	Bassam Alrifaee & Patrick Scheffe			
UTC+01:00	Monday	Tuesday	Wednesday	Thursday	Friday	
09:00-9:30	Introduction	Control	Network	Lab: DMPC		
9:30-10:00	introduction				Control	
10:00-10:30	Models					
10:30-11:00	Break	Break	Break	Break	Break	
11:00-11:30		Lab: Basics	Lab: CMPC	Lab: DMPC	Presentation	
11:30-12:00	Models					
12:00-12:30					Wrap-up	
12:30-13:00		Break	Lab: Team Work		Assessment	
13:00-13:30	Break				Certificates	
13:30-14:00						
14:00-14:30		Network				
14:30-15:00	Architectures			Lab: Team Work		
15:00-15:30						
15:30-16:00	Break	Break				
16:00-16:30						
16:30-17:00	16:30-17:00 Lab: Basics					
17:00-17:30						

19:00-21:00		Social Event	
Lecture	CPM Lab		

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![](_page_25_Picture_4.jpeg)

## **Some Terms**

### Levels of automation

## SAE J3016 from Society of Automotive Engineers (SAE)

- Level 0
- Level 1 ("hands on")
- Level 2 ("hands off")
- Level 3 ("eyes off")
- Level 4 ("mind off")
- Level 5 ("steering wheel optional")
- US National Highway Traffic Safety Administration (NHTSA)
- German Federal Highway Research Institute (BASt)

![](_page_27_Picture_10.jpeg)

## **Definition of networked vehicles**

- Also called connected
- Vehicle-to-X communications
- Consists of interacting vehicles
- Contribution to better
  - Perception
  - Decision-making
- Many challenges arising from computation time and communications
  - Feasibility
  - Quality

![](_page_28_Picture_10.jpeg)

### **Next Part**

#### **Vehicle models**

- Longitudinal models
- Lateral models

![](_page_30_Picture_3.jpeg)